Finite Element Galerkin’s Approach for Viscous Incompressible Fluid Flow through a Porous Medium in Coaxial Cylinders

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Abstract In this paper, we are considering viscous incompressible fluid flow through a porous medium between two coaxial cylinders. The governing equations have been solved by using Finite element Galerkin’s approach. The velocity and temperature profiles of the flow are computed numerically and their behaviours are discussed by graphs for different values of the parameters.

Keywords: coaxial cylinder, Galerkin’s scheme, porous medium, viscous flow


1. Introduction


In this paper, we have analysed the free and forced convection of viscous fluid flow in coaxial cylinders taking into account the viscous dissipation. The governing equations have been solved by using Galerkin’s approach. The velocity and temperature profiles of the fluid flow are computed numerically and their behaviour is discussed by graphs for different values of the governing parameters.

2. Mathematical Analysis
In the present investigation, we are considering a fully developed steady laminar free and forced convective flow of viscous incompressible fluid through a porous medium in between two vertical coaxial cylinders. Suppose \( \{r^*, \varphi^*, z^*\} \) be the cylindrical coordinate system such that \( r^* = a \) and \( r^* = b \) are the radii of inner and outer cylinders respectively. Assuming that the pipes are long enough so that all the physical quantities are independent of \( \varphi^* \) and \( z^* \). The motion being rotationally symmetric so the azimuthal velocity is zero. The governing equations in non-dimensional form are given by,

\[
\frac{d^2 w}{dr^2} + \frac{1}{r} \frac{dw}{dr} = P + G_r \frac{w}{D} - K w, \tag{1}
\]

\[
\frac{d^2 \theta}{dr^2} + \frac{1}{r} \frac{d\theta}{dr} + \left(\frac{dw}{dr}\right)^2 = 0, \tag{2}
\]

where

\[ r^* = a, w = \frac{aw^*}{\nu}, P^* = \frac{P_0 + P}{T_0 - T}, \theta = \frac{T^* - T_0}{T_1 - T_0}, P = \frac{a^2}{\rho \alpha^2} \left(\frac{-\partial \varphi^*}{\partial z^*}\right), \]

\( w \) is the non-dimensional velocity component along z-axis, \( \rho \) the density of the fluid, \( P \) the fluid pressure, \( T \) the non-dimensional temperature of the fluid, \( \mu \) the coefficient of viscosity, \( C_p \) the specific heat at constant pressure, \( \nu \) the kinematic viscosity, \( K \) the permeability of porous medium, \( k \) the coefficient of thermal conductivity, \( \rho_0 \) the equilibrium density, \( T_0 \) the equilibrium temperature, \( P_s \) the equilibrium pressure and \( P_D \) the dynamic pressure. \( K_1 \) Porosity,

\[ G_r = \frac{g \beta (T_1 - T_0)}{\nu^2} \quad (\text{Grashof number}) \]

\[ h = \frac{\mu \nu^2}{k (T_1 - T_0)} \quad (\text{Eckert number}), \]

\[ D^{-1} = \frac{a^2}{K} \quad (\text{Darcy’s parameter}), \]

and \( P = \frac{-\partial \varphi}{\partial z} \) (Pressure gradient).

The hydrostatic balance equation gives

\[-\frac{\partial P}{\partial z} - \rho_0 g = 0, \tag{3}\]

The corresponding boundary conditions are:

\[ w(1) = w(s) = 0, \quad \theta(1) = 0, \quad \theta(s) = 1, \quad \text{where} \quad s = \frac{b}{a}. \tag{4}\]

### 3. Numerical Method

In order to solve equations (1) and (2) under the boundary conditions (4), the finite element method of Galerkin’s approach has been used. In Galerkin’s method the weight function is equal to the approximation function.

Suppose domain \( (r_a, r_b) \) of the radial direction is divided into \( n \) subintervals and length of each interval is \( h_k = (r_b - r_a)/n \), where \( s = n_a/r_a \) (the gap duct between two coaxial cylinders) Kumar et al [2013].

The Galerkin’s scheme is defined by

\[ \int_{\Omega} \varepsilon \varphi_i d\Omega = 0, \tag{5}\]

where \( \varepsilon \) is residual function and \( \varphi_i \) weighting function.

From equation (1), we have residual function

\[ -\frac{d^2 w}{dr^2} - \frac{1}{r} \frac{dw}{dr} = \frac{1}{D} \left(1 + K_1\right) w + P + G_r \theta. \]

We use the Galerkin’s integral in the form

\[ -\int_{\Omega} \left[\frac{d^2 w}{dr^2} + \frac{1}{r} \frac{dw}{dr} + \frac{1}{D} \left(1 + K_1\right) w - P - G_r \theta\right] \varphi_i d\Omega = 0, \tag{6}\]

where \( \Omega \) is the volume of the annulus bounded by coaxial cylinders of unit length. The weak form of the equation (6) is given below:

\[ -\int_{r_a}^{r_b} \int_{\varphi_i}^{d\theta_i} \left[ \frac{d}{dr} \left( \frac{d w}{dr} \right) \right] d\Omega = 0. \tag{7}\]

Integrating equation (7) by parts, we get

\[ \int_{r_a}^{r_b} \int_{\varphi_i}^{d\theta_i} \left[ \frac{d}{dr} \left( \frac{d w}{dr} + \frac{1}{D} \left(1 + K_1\right) w - P - G_r \theta \right) \right] d\Omega = 0. \]

Or

\[ \int_{r_a}^{r_b} \left[ \frac{d}{dr} \left( \frac{d w}{dr} + \frac{1}{D} \left(1 + K_1\right) w - P - G_r \theta \right) \right] d\Omega = 0. \]

Here

\[ Q_1^e = \frac{r_a}{a} \left( \frac{d w}{dr} \right)_{r=r_a} \quad \text{and} \quad Q_2^e = \frac{r_a}{a} \left( \frac{d w}{dr} \right)_{r=r_b}. \]

Similarly, weak form of equation (2) can be expressed as

\[ \int_{r_a}^{r_b} \frac{d^2 \theta}{dr^2} d\Omega = 0. \]

Or

\[ \int_{r_a}^{r_b} \left[ \frac{h}{k} \left( \frac{d w}{dr} \right)^2 \right] d\Omega = 0. \]

Where \( T_1^e = r_a^2 \left( \frac{d \theta}{dr} \right)_{r=r_a} \) and \( T_2^e = r_a^2 \left( \frac{d \theta}{dr} \right)_{r=r_b}. \)
Let us assume that \( w(r) = \sum_{j=1}^{n} w_j \psi_j(r) \) and \( \theta(r) = \sum_{j=1}^{n} \theta_j \psi_j(r) \) are the approximate solutions of the equations (1) and (2). Assuming \( \phi_j = \psi_1, \psi_2, \psi_3, \ldots, \psi_n \) (weight function is equal to the approximation function). Therefore the Finite element model for velocity and temperature profiles are given by

\[
[K^e][w^e] = [f^e][Q^e], \tag{8}
\]

\[
[S^e][\theta^e] = [g^e][T^e], \tag{9}
\]

where

\[
K^e_{ij} = \int_{r_a}^{r_b} \left[ r^2 \frac{d \psi_i r}{dr} \frac{d \psi_j r}{dr} + \left( \frac{1}{D} + K_1 \right) w_j \psi_i r \right] dr,
\]

\[
f^e_j = \int_{r_a}^{r_b} \left( \frac{P + G \theta}{} \psi_j r \right) dr, \quad K^e_{ij} = \int_{r_a}^{r_b} \left[ r^2 \frac{d \theta r}{dr} \frac{d \psi_j r}{dr} \right] dr,
\]

\[
g^e = -\int_{r_a}^{r_b} \left( \frac{r_b - r}{h} \right)^2 \psi_2 r dr.
\]

Taking the approximate function as a linear interpolation function of the form \( \psi_1 = \frac{r_b - r}{h} \), \( \psi_2 = \frac{r - r_a}{h} \).

The equations (8) and (9) are the standard Galerkin’s finite elements equations. Their solutions can be obtained by Predictor-Corrector method.

### 4. Results and Discussion

The free and forced convection flow of viscous incompressible fluid through coaxial cylinders is discussed taking into account the viscous dissipation effects.

Here \( G_r > 0 \) indicates that the temperature of the outer boundary is higher than the inner in a coaxial cylinder duct or vice versa \( G_r < 0 \).

Figure 1. Velocity Profiles for Various Number of Grashoff Number \( G_r \), \( (s = 1.1, P = 1, D^{-1} = 10000, h = 0.001, K_1 = 0.732) \)

Figure 2. Velocity Profiles for Various Values \( D^{-1} \), \( (s = 1.1, P = 1, G_r = 400, h = 0.001, K_1 = 1) \)

Figure 3. Temperature Profiles for Different Values of Grashoff Number \( G_r \), \( (s = 1.1, P = 1, D^{-1} = 10000, h = 0.001, K_1 = 0.732) \)

Figure 4. Temperature Profiles for Different Values \( D^{-1} \), \( (s = 1.1, P = 1, G_r = 400, h = 0.001, K_1 = 0.732) \)

Figures 1 and 5 show that the axial velocity of the fluid be maximum at the mid region while velocity profile upwards for \( G_r > 0 \) and downwards for \( G_r < 0 \). From these figures we observe that the enhancement in the velocity profile depends upon the nature of the gap duct between two coaxial cylinders. The magnitude of the axial velocity in narrow gap duct is less than that of wider gap duct for a given Grashoff number \( G_r \). Figures 2 and 6 depict that the velocity profile increases with the increasing values of Darcy’s parameter \( D^{-1} \) in both narrow and wider gap duct while the enhancement in the wider gap duct is higher than to the narrow gap duct. Figure 3 depicts that the temperature profiles for various values of \( G_r \) in a narrow gap duct. Figure 4 depicts that the temperature profiles for various values of Darcy’s parameter \( D^{-1} \). The temperature profile increases with the decrease in the permeability of the porous medium and effect of magnetic field. Figure 7 and Figure 8 depict that the temperature profiles for various values of Grashoff number \( G_r \) and \( D^{-1} \) respectively in wide gap duct of the coaxial cylinders. The temperature assumes positive values faster as we move from the inner boundary to outer boundary than in the case of narrow gap duct. The nature of temperature profile in wider gap duct of coaxial cylinders.
for positive or negative values of $G_r$, $D^{-1}$ is similar to that of the corresponding case in a narrow gap duct of the coaxial cylinders. The present algorithm is economic and efficient having a sharp convergence.

**Figure 5.** Velocity Profiles for Different Values of Grashoff Number $G_r$, ($s = 1.5, P = 1, D^{-1} = 10000, h = 0.001, K_1 = 0.732$)

**Figure 6.** Velocity Profiles for Different Values $D^{-1}$, ($s = 1.5, P = 1, G_r = 400, h = 0.001, K_1 = 1$)

**Figure 7.** Temperature Profiles for Different Values of Grashoff number $G_r$, ($s = 1.5, P = 1, D^{-1} = 10000, h = 0.001, K_1 = 0.732$)

**Figure 8.** Temperature Profiles for Different Values $D^{-1}$, ($s = 1.5, P = 1, G_r = 400, h = 0.001, K_1 = 1$)

### References


