A New Mechanism for Congestion Control in Wireless Multimedia Sensor Networks for Quality of Service and Network Life Time

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Abstract In wireless multimedia sensor networks (WMSNs) a sensor node may have different types of sensor which gather different kinds of data. To support quality of service (QoS) requirements for multimedia applications having a reliable and fair transport protocol is necessary. One of the main objectives of the transport layer in WMSNs is congestion control. We observe that the information provided may have different levels of importance and argue that sensor networks should be willing to spend more resources in disseminating packets carrying more important information. In WMSN event-driven applications, it is critical to report the detected events in the area, resulting in sudden bursts of traffic due to occurrence of spatially-correlated or multiple events, causing loss of data. Also, nodes have very limited power due to hardware constraints. Packet losses and retransmissions resulting from congestion, cost precious energy and shorten the lifetime of sensor nodes. Till now, in WMSNs, Congestion control techniques are based on detection of congestion and recovery, but they cannot eliminate or prevent the occurrence of congestion. Collision is a symptom of congestion in the wireless channel and can result in a time-variant channel capacity. The main intention of this protocol is to be used as a mechanism for reducing congestion in the network by free resources to set accurate rates and priority data needs. If two nodes send their packets in the shortest path to the parent node in a crowded place, a source node must prioritize the data and uses data that have lower priorities of a suitable detour nodes consisting of low or non- active consciously. Proposed algorithm is applied to the nodes near the base station (which convey more traffic) after the congestion detection mechanism detected the congestion. The results obtained from simulation test done by NS-2 simulator indicate that the proposed model is more innovative and presents better performance in compare with CCF, PCCP and DCCP protocols.

Keywords: wireless multimedia sensor networks, congestion control, energy, collision


1. Introduction

Most of the research before in the wireless sensor network (WSN) is concerned with scalar sensor networks that measure physical phenomena, such as pressure, temperature, humidity, or location of objects that can be conveyed through low bandwidth and delay-tolerant data streams. Recently, the focus is shifting toward research aimed to enable delivery of multimedia content, such as audio and video streams, as well as scalar data. This effort resulted in distributed, networked systems, referred to by Ref. [1] as WMSNs. Due to limited resources, QoS becomes a huge challenge in WMSNs, of which one prominent issue to be addressed in this paper is congestion control.

For WMSNs where wireless channels are shared by several motes using carrier sense multiple access (CSMA-like) protocols, collisions could occur when multiple active sensor motes try to seize the channel at the same time. This can be referred to as link-level congestion. Link-level congestion increases packet service time, and decreases both link utilization and overall throughput, and wastes energy of the sensor motes. There is another type of congestion called node-level congestion which is common in conventional networks. It is caused by buffer overflow in the mote and can result in packet loss, and increase latency. Packet loss in turn can lead to retransmission and therefore wastes more energy. Both link-level and node-level congestions (illustrated in Figure 1) have direct impact on energy efficiency and QoS.

This research has been formed as follows; section II includes a summary of related works and describes some of the WMSNs protocols.

This Section is related to the issues encountered during designing different types of congestion and congestion control in WMSNs. Proposed method is given in section III. Section IV gives us an evaluation of simulation results and the conclusion of the research is included in section VI.
2. Brief Review of Congestion Control in WMSNs

Prior work in sensor networks literature has broadly looked at two qualitatively different problems, viz., congestion mitigation and congestion control. In general, congestion mitigation looks at the following problem. If in a sensor network, the nodes are provisioned to sense the environment and send periodic samples at a fixed rate, then, when the aggregate traffic exceeds the network capacity, how should the nodes regulate their transmissions so that the network goodput and fairness degrade gracefully. This is different from congestion control, which seeks to find an optimal fair rate for the sensor nodes that is also maximally efficient.

In this case, when the nodes transmit data at the optimal rate, the network is maximally utilized, and the per node goodput is close to the sending rate. Adaptive Rate Control (ARC) monitors the injection of packets into the traffic stream as well as route-through traffic. Each node estimates the number of upstream nodes and the bandwidth is split proportionally between route-through and locally generated traffic, with preference given to the former. The resulting bandwidth allocated to each node is thus approximately fair. Also, reduction in transmission rate of route-through traffic has a backpressure effect on upstream nodes, which in turn can reduce their transmission rates.

In [16], the authors propose Congestion Detection and Avoidance (CODA). CODA uses several mechanisms to alleviate congestion. In open-loop hop-by-hop backpressure, when a node experiences congestion, it broadcasts back-pressure messages upstream towards the source nodes, informing the mof the need to reduce their sending rates. In closed-loop multi-source regulation, the sink asserts congestion control over multiple sources. Acknowledgement (ACKs) are required by the sources to determine their sending rates when traffic load exceeds the channel capacity. In general, open-loop control is more appropriate for transient congestion, while, closed loop control is better for persistent congestion.

In [14], the authors propose the event-to-sink reliable transport protocol. ESRT allocates transmission rates to sensors such that an application-defined number of sensor readings are received at the sink, while ensuring the network is uncongested. The rate allocation is centrally computed at the base station. ESRT monitors the local buffer level of sensor nodes and sets a congestion notification bit in the packets it forwards to the sink if the buffer overflows.

If a sink receives a packet with the congestion notification bit set, it infers congestion and broadcasts a control signal informing all sources to reduce their common reporting frequency. However, this approach suffers from a few drawbacks.

Firstly, since the sink must broadcast this control signal at a high energy to allow all the sources to hear it, an ongoing event transmission can be disrupted by this high powered congestion signal. Moreover, rate regulating all sources as proposed in [14], is fine for homogeneous applications, where all sensors in the network have the same reporting rate but not for heterogeneous ones.

Even with a network where all the sources have a uniform reporting rate, ESRT always regulates all sources regardless of where the hotspot occurs in the sensor network.

The control law used by ESRT is based on empirically derived regions of operation, and does not attempt to find a fair and efficient rate allocation for the nodes. Fusion [5] is a congestion mitigation technique that uses queue lengths to detect congestion. Fusion uses three different techniques to alleviate congestion, viz, hop-by-hop flow control, rate limiting, and a prioritized MAC. Hop-by-hop flow control prevents nodes from transmitting if their packets are only destined to be dropped downstream due to insufficient buffer spaces. Rate limiting meters traffic being admitted into the network to prevent unfairness towards sources far away from the sink. Prioritized MAC ensures that congested nodes receive prioritized access to the channel, allowing output queues to drain. Fusion focuses on congestion mitigation and does not seek to find an optimal transmission rate for the nodes that is both fair and efficient. In [13], the authors proposed the Interference Aware Fair Rate Control protocol (IFRC). IFRC is a distributed rate allocation scheme that uses queue sizes to detect congestion, and further shares the congestion state through overhearing. Congestion Control and Fairness for Many-to-one Routing in Sensor Networks [3] is another rate allocation scheme that uses a different mechanism than IFRC.

Both IFRC and [3] are tangentially related to our work in the sense that they attempt to find optimal transmission rates for all nodes, such that, congestion collapse is avoided. Note that, our algorithm has greater flexibility than IFRC and [3], since many different traffic allocation policies can be implemented in our congestion control scheme, without changing the basic congestion control module (the utility controller).

Moreover, IFRC suffers from the additional drawback of having sophisticated parameter tuning for stability, unlike ours. In [11], the authors propose the Rate Controlled Reliable Transport protocol (RCRT). This protocol is built for loss-tolerant applications that require reliable transport of data from the source nodes to the sink. RCRT uses end-to-end explicit loss recovery by implementing a NACK based scheme.

Furthermore, RCRT places all congestion detection and rate adaptation functionality in the sinks, thereby producing a centralized congestion control scheme. The authors in [9] proposes a congestion control mechanism, in which, the buffer in each node is adjusted according to the transmitting downstream nodes in order to minimize packet drop; the algorithm automatically adjusts a node’s forwarding rate to avoid packet drops due to congestion. The algorithm resolves the fairness problem by allocating equal bandwidth to the sources. The authors in [12]
propose a rate-based fairness-aware congestion control (FACC) protocol, which controls congestion and achieves approximately fair bandwidth allocation for different flows.

Their congestion control is based on probabilistic dropping based on queue occupancy and hit frequency. Our congestion control is in contrast to these works as it abstracts the notion of fairness, allowing it to assume different fairness models, such as weighted fairness. In [13], the authors propose a hop by hop predictive congestion control scheme for WSNs.

Their algorithm detects the onset of congestion using queue utilization and a channel estimator algorithm that predicts the channel quality. Flow control is then achieved by a back off interval selection scheme.

Though, in this paper, we focus on congestion control in sensor networks, it will not be out of place to discuss some recent work on congestion control in wireless network in general. The authors in [12] propose a cross-layer optimization scheme for congestion control in multi-hop wireless networks.

They implement a differential backlog based MAC scheduling and router-assisted backpressure congestion control scheme using real off-shelf radios. In the authors focus on fair bandwidth sharing between end-to-end flows, while maintaining an efficient overall throughput in the network.

They propose a dynamic rate allocation solution that is based on a simple radio sharing model. In the next section, we will formulate our problem and also discuss the rationale behind our solution approach.

Various congestion control methods have been studied for wireless sensor networks. Among them, most popular techniques are CCF, PCCP and DCCP.

As was shown in [6], CCF is a non-work-conserving algorithm. To explain the non-work-conserving property of CCF, suppose that a root node is connected to two nodes A and B. The non-work-conserving property of CCF implies that the root node will wait until the required number of packets has been received and transmitted from node B before considering packets from node A. This also implies that CCF cannot effectively allocate the remaining capacity, resulting in a low throughput, especially, when some nodes do not have any packet to send. Further, as was shown in [6], CCF has another major problem. The rate adjustment in CCF relies only on packet service time which could lead to low utilization when some sensor nodes do not have enough traffic or there is a significant packet error rate.

Priority based congestion control protocol (PCCP) was proposed in [6].

PCCP is an upstream congestion control protocol for WSNs which measures the congestion degree as the ratio of packet inter-arrival time to the packet service time. Based on the introduced congestion degree and node priority index, PCCP utilizes a cross-layer optimization and imposes a hop-by-hop approach to control congestion. It has also been shown that PCCP achieves efficient congestion control and flexible weighted fairness for both single-path and multipath routing. In wireless sensor networks data are normally generated and sent to the sink periodically. However, a burst of data traffic can also be suddenly generated when an important event is triggered or detected. So, in wireless sensor networks different data packets might have different importance. For packets containing information with higher importance, the network should make more effort in delivering them. This highlights a need for having service differentiation in sensor networks. Service differentiation in wireless sensor networks is a new research area and a few methods have been proposed [6].

The Datagram Congestion Control Protocol (DCCP) is a message-oriented transport layer protocol. DCCP implements reliable connection setup, teardown, Explicit Congestion Notification (ECN), congestion control, and feature negotiation. DCCP was published as RFC 4340, a proposed standard, by the IETF in March, 2006. RFC 4336 provides an introduction. FreeBSD had an implementation for version 5.1 [1]. Linux also had an implementation of DCCP first released in Linux kernel version 2.6.14 (released October 28, 2005).

DCCP provides a way to gain access to congestion control mechanisms without having to implement them at the application layer. It allows for flow-based semantics like in Transmission Control Protocol (TCP), but does not provide reliable in-order delivery. Sequenced delivery within multiple streams as in the Stream Control Transmission Protocol (SCTP) is not available in DCCP.

DCCP is useful for applications with timing constraints on the delivery of data. Such applications include streaming media, multiplayer online games and Internet telephony.

The primary feature of these applications is that old messages quickly become stale so that getting new messages is preferred to resending lost messages. Currently such applications have often either settled for TCP or used User Datagram Protocol (UDP) and implemented their own congestion control mechanisms, or have no congestion control at all.

While being useful for these applications, DCCP can also be positioned as a general congestion control mechanism for UDP-based applications, by adding, as needed, a mechanism for reliable and/or in-order delivery on the top of UDP/DCCP. In this context, DCCP allows the use of different, but generally TCP-friendly congestion control mechanisms [8].

3. Details of the Proposed Scenarios

The proposed method called reliability and congestion control protocol that has two basic functions responsible for the reliability and congestion control.

The main intention of this protocol is to be used as a mechanism for reducing congestion in the network by free resources to set accurate rates and priority data needs.

If two nodes send their packets in the shortest path to the parent node in a crowded place, a source node must prioritize the data and uses data that have lower priorities of a suitable detour nodes consisting of low or non-active consciously.

Due to the limited energy of sensor node, existing trails will be used instead of creating new routes.

The proposed protocols are tried to increase network lifetime and the rate of successful packet transfer by reduction of possibility of packet loss as much as possible.

As we know there are two types of traffic at each node, local traffic and transmitted traffic. In fact, each node can
act as a source and as a routers in the network. Source traffic is created locally and by the node itself if the transmitted traffic is created through other nodes and are sent to the upstream node to be sent to the scrap.

As can be inferred, the tree structure has a kind of injustice in terms of bandwidth allocation for sensor network nodes located at different levels so that nodes near the sink are given a higher priority but farther nodes have to send data through intermediate nodes, passing several steps with great delay.

To solve this problem, the proposed algorithm uses a priority mechanism. Each packet contains two types of real-time and non-real-time priority. Immediate priority is an integer constant and the minimum value for the priority of a packet is equal to zero.

Immediate priorities of the packet varies based on parameters of the number of steps elapsed like ageing algorithm, in such a way that much greater chance for larger number of the immediate packet. In equations 1 the proposed congestion control protocols presented.

In general case, proposed algorithm is not applied in normal case since computation is a time consumer manner. Proposed algorithm is applied to the nodes near the base station (which convey more traffic) after the congestion detection mechanism detected the congestion.

4. Simulation Results

We choose NS-2 simulator for simulation because it’s flexible and better performance. Values assigned to the parameters for simulation are Table 1.

We compared our Model with CCF, PCCP and DCCP protocols. This is the reason that the proposed model shows average delay and packet loss in Figure 2 and Figure 3.

<table>
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<th>Table 1. Values of Parameters for simulation</th>
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<td>Simulator</td>
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Figure 2. Average Network Delay

Figure 3. Packet Loss
Congestion control is directly related to energy consumption, the Figure 4 expresses this fact that proposed model optimize the energy consumption and have a longer network lifetime in comparison with CCF, PCCP and DCCP protocols.

Figure 4. Power Consumption Network

Figure 5 and Figure 6 illustrated that, proposed model is better in terms of average throughput and packet delivery ratio respectively.

Figure 5. Average Network Delay

Figure 6. Packet Loss

5. Conclusion

New applications made possible by rapid improvements and miniaturization in hardware has motivated recent developments in wireless multimedia sensor networks (WMSNs). To provide the required quality of service for multimedia applications in WMSNs, congestion control is necessary. Each congestion control protocol should be able to detect congestion in advance, and allocate available rates to the sensor nodes accordingly. For some applications, there is a need to send real time traffic toward the sink node with low latency and high reliability so that immediate remedial and defensive actions can be taken, as appropriate. Further, when an important event occurs in the system, the sensor node that detected the event should send some alarm message to the sink. Usually this kind of high priority traffic is bursty. This means that high priority traffic is generated only for a short period of time while low priority traffic usually exists in the network and produce thousands of packets generated periodically. For such environments, service differentiation in wireless multimedia sensor networks becomes an important problem. To provide service differentiation in WMSNs, it is necessary to consider a different priority for each traffic source.

In this paper we presented a model for congestion control in WMSNs. The main intention of this protocol is to be used as a mechanism for reducing congestion in the network by free resources to set accurate rates and priority data needs. If two nodes send their packets in the shortest path to the parent node in a crowded place, a source node must prioritize the data and uses data that have lower priorities of a suitable detour nodes consisting of low or non-active consciously. proposed algorithm is not applied in normal case since computation is a time consumer manner. Proposed algorithm is applied to the nodes near the base station (which convey more traffic) after the congestion detection mechanism detected the congestion.

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